# A FAST ALGORITHM FOR COMPUTING A MINIMAL DECOMPOSITION OF A METABOLIC FLUX VECTOR IN TERMS OF ELEMENTARY FLUX VECTORS 

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#### Abstract

The concept of elementary flux vector is valuable in a number of applications of metabolic engineering. For instance, in metabolic flux analysis, each admissible flux vector can be expressed as a non-negative linear combination of a small number of elementary flux vectors. However a critical issue concerns the number of elementary flux vectors which may be huge because it combinatorially increases with the size of the metabolic network. In this paper we present a fast algorithm that randomly computes admissible flux vectors having a minimal decomposition without explicitely enumerating all the elementary flux vectors of the network. The method is illustrated with an experimental casestudy on CHO cells where the network has 65329 elementary flux vectors while the admissible flux distributions are expressed as a combination of 22 elementary vectors only.


## 1 Metabolic networks and elementary flux vectors

The intracellular metabolism of living cells is usually represented by a metabolic network under the form of a directed hypergraph that encodes a set of biochemical reactions taking place within the cell. In this hypergraph, the nodes represent the metabolites and the edges represent the metabolic fluxes.

According to the quasi steady-state paradigm of metabolic flux analysis (MFA) (e.g. [10]), it is assumed that the fluxes are balanced at each internal node. This means that the net sum of production and consumption fluxes, weighted by their stoichiometric coefficients, is zero for each internal metabolite of the network. This is expressed by the algebraic relation:

$$
\begin{equation*}
\mathbf{N} \mathbf{v}=\mathbf{0} \quad \mathbf{v} \geqslant \mathbf{0} \tag{1}
\end{equation*}
$$

where $\mathbf{v}=\left(v_{1}, v_{2}, \ldots, v_{m}\right)^{T}$ is the $m$-dimensional column vector of fluxes and $\mathbf{N}=\left[n_{i j}\right]$ is the $n \times m$ stoichiometric matrix of the metabolic network ( $m$ is the number of fluxes and $n$ the number of internal nodes of the network). More precisely, a flux $v_{j}$ denotes the rate of reaction $j$ and a non-zero $n_{i j}$ is the stoichiometric coefficient of the metabolite $i$ in reaction $j$.

For a given metabolic network, the set $S$ of possible flux distributions is the set of vectors $\mathbf{v}$ that satisfy the linear system (1). This set $S$ is the pointed polyhedral cone resulting from the intersection of the kernel of $\mathbf{N}$ with the nonnegative orthant. This implies that there exists a set of elementary flux vectors $\mathbf{e}_{i}$ ([11]) which are the edges (or extremal rays) of the polyhedral cone and such that any flux distribution $\mathbf{v}$ can be expressed as a non-negative linear combination of the vectors $\mathbf{e}_{i}$ which form therefore a unique convex basis (see e.g. [12]) of the flux space $S$ :

$$
\begin{equation*}
\mathbf{v}=w_{1} \mathbf{e}_{1}+w_{2} \mathbf{e}_{2}+\cdots+w_{q} \mathbf{e}_{q} \quad w_{i} \geqslant 0 . \tag{2}
\end{equation*}
$$

The $m \times q$ non-negative matrix $\mathbf{E}$ with column vectors $\mathbf{e}_{i}$ obviously satisfies $\mathbf{N E}=0$ and (2) can be written in matrix form as

$$
\begin{equation*}
\mathbf{v}=\mathbf{E w} \quad \text { with } \mathbf{w} \triangleq\left(w_{1}, w_{2}, \ldots, w_{q}\right)^{T} . \tag{3}
\end{equation*}
$$

## 2 Metabolic flux analysis

Metabolic flux analysis (MFA) is the exercise of calculating the admissible flux distributions $\mathbf{v}$ that satisfy the steady state balance equation $\mathbf{N v}=\mathbf{0}$ together with an additional set of linear constraints added by using experimental measurements. Here we consider the case where the measurements are collected in a vector $\mathbf{v}_{m}$ which is a linear function of the unknown flux distribution $\mathbf{v}$ and is expressed as

$$
\begin{equation*}
\mathbf{v}_{m}=\mathbf{P} \mathbf{v} \tag{4}
\end{equation*}
$$

where $\mathbf{P}$ is a given $p \times m$ full-rank matrix. In addition, it is assumed that $\mathbf{P e}_{i} \neq 0 \forall i$ or, in other terms, that the elementary flux vectors $\mathbf{e}_{i}$ do not belong to the kernel of the matrix $\mathbf{P}$. Then, from equations (1)-(4), we have the following fundamental equation of metabolic flux analysis

$$
\Sigma\binom{\mathbf{v}}{1}=\mathbf{0} \text { with } \Sigma \triangleq\left(\begin{array}{cc}
\mathbf{N} & \mathbf{0}  \tag{5}\\
\mathbf{P} & -\mathbf{v}_{m}
\end{array}\right) \text { and } \mathbf{v} \geqslant \mathbf{0} .
$$



Figure 1: Illustration of the flux spaces $S$ and $\mathscr{F}$.

For a given metabolic network and a given set of measurements, the solution of the MFA problem is defined as the set $\mathscr{F}$ of admissible flux distributions i.e. the set of non-negative vectors $\mathbf{v}$ that satisfy the homogeneous linear system (5). Each admissible $\mathbf{v}$ must be such that the non-negative vector $\left(\mathbf{v}^{T} 1\right)^{T}$ belongs to the kernel of the matrix $\Sigma$. Hence, as emphasized in [7, Chapter 4]-[8], the set $\mathscr{F}$ is a polytope in the positive orthant $\mathbb{R}_{+}^{m}$. This means that any admissible flux distribution $\mathbf{v}$ can be expressed as a convex combination of a set of non-negative basis vectors $\mathbf{f}_{i}$ which are the vertices of this polytope and form therefore a unique convex basis of the flux space $\mathscr{F}$. In other words, the solution of the MFA problem is the admissible flux space $\mathscr{F}$ defined as

$$
\begin{equation*}
\mathscr{F} \triangleq\left\{\mathbf{v}: \mathbf{v}=\sum_{i} \alpha_{i} \mathbf{f}_{i}, \quad \alpha_{i} \geqslant 0, \sum_{i} \alpha_{i}=1\right\} \tag{6}
\end{equation*}
$$

The admissible flux space $\mathscr{F}$ is a subset of the possible flux space $S$. In geometric terms, the polytope $\mathscr{F}$ defines a subcone of the pointed cone $S$ as illustrated in Fig.1.

## 3 Minimal decomposition of $\mathbf{v} \in \mathscr{F}$ in terms of elementary vectors $\mathbf{e}_{i}$

For any admissible flux vector $\mathbf{v}$ in the polytope $\mathscr{F}$ satisfying equation (5), it must be emphasized that the decomposition of $\mathbf{v}$ in the convex basis $\left\{\mathbf{e}_{i}\right\}$ is not unique. Our aim is to determine minimal decompositions which can be useful in pratical applications of MFA. Using (3), system (5) is equivalent to the system:

$$
\begin{equation*}
\binom{\mathbf{N E}}{\mathbf{P E}} \mathbf{w}=\binom{\mathbf{0}}{\mathbf{v}_{m}} \quad \mathbf{w} \geqslant 0 \tag{7}
\end{equation*}
$$

We observe that the first equation $\mathbf{N E w}=\mathbf{0}$ is trivially satisfied independently of $\mathbf{w}$ since by definition $\mathbf{N E}=0$. Hence, system (7) may be reduced to the second equation:

$$
\mathbf{P E w}=\mathbf{v}_{m} \quad \mathbf{w} \geqslant \mathbf{0} .
$$

or equivalently:

$$
\left(\begin{array}{ll}
\mathbf{P E} & -\mathbf{v}_{m} \tag{8}
\end{array}\right)\binom{\mathbf{w}}{1}=0 \quad \mathbf{w} \geqslant \mathbf{0} .
$$

In this form, it is clear that the set of admissible weighting vectors $\mathbf{w}$ that satisfy (8) again constitutes a convex polytope that we denote $\mathscr{H}$. Therefore there exists a set of appropriate edge vectors $\mathbf{h}_{i}$ such that any arbitrary convex combination of the form:

$$
\begin{equation*}
\mathbf{w}=\sum_{i} \beta_{i} \mathbf{h}_{i} \quad \beta_{i} \geqslant 0 \quad \sum_{i} \beta_{i}=1 \tag{9}
\end{equation*}
$$

is necessarily an admissible $\mathbf{w}$ satisfying (8). The convex basis vectors $\mathbf{h}_{i}$ have a critical property : the number of non-zero entries is equal to the size $p$ of the vector $\mathbf{v}_{\mathbf{m}}$ i.e. the number of measurements (see [3] and Section 3.5 in [7]). From a metabolic viewpoint, each vector $\mathbf{h}_{i}$ is a particular solution $\mathbf{w}$ of (8) corresponding to an admissible flux distribution $\mathbf{v}$ :

$$
\begin{equation*}
\mathbf{v}=\mathbf{E h}_{i} \quad \mathbf{v} \in \mathscr{F} \tag{10}
\end{equation*}
$$

In this expression, the non-zero entries of the vector $\mathbf{h}_{i}$ are interpreted as the weights of the respective contributions of the corresponding elementary flux vectors $\mathbf{e}_{i}$ in the computation of the flux distribution $\mathbf{v}$.
An important issue concerns the number of distinct extremal rays or vertices that are generated when computing the cone $S$ or the polytopes $\mathscr{F}$ and $\mathscr{H}$. This number may become very large because it combinatorially increases with the size of the underlying metabolic network. The Double Description (DD) method ([6]) is the simplest known algorithm for enumerating the extremal rays of a polyhedral cone (see [3] for a review). In the context of metabolic networks it has received various dedicated improvements that are documented in the literature (see e.g. [9], [4] and [5]). In practical applications of MFA, the enumeration of all extremal rays is not necessarily a
critical objective. In many applications it is sufficient to know only one minimal decomposition of some vectors $\mathbf{v} \in \mathscr{F}$ in terms of elementary vectors $\mathbf{e}_{i}$. It clearly follows from our analysis that such a minimal decomposition involves $\ell$ terms with $p \leqslant \ell \leqslant(m-n)$. Furthermore, according to (10) there necessarily exist admissible $\mathbf{v}$ having a decomposition that involves only $p$ terms. Computing this decomposition may be very expensive at first sight since the dimension of $\mathbf{E}$ is not bounded by a polynomial in the sizes of $\mathbf{N}$ and $\mathbf{P}$.
In this paper we present a fast algorithm that randomly computes vectors $\mathbf{v} \in \mathscr{F}$ having such a minimal decomposition from the sole knowledge of the stoichiometric matrices $\mathbf{N}, \mathbf{P}$ and the measurement vector $\mathbf{v}_{m}$ but without explicitely enumerating the extremal rays of the cone $S$ (i.e. the columns of the huge matrix $\mathbf{E}$ ) and therefore without solving the system (8).

## 4 The algorithm

Let us first consider the following simple problem: We are given a vector $\mathbf{v}$ that belongs to a cone $S$, and we would like to express this vector as a linear combination of a few extremal rays of $S$.
Let us denote $a=\mathbf{u}^{T} \mathbf{v}$ the sum of the entries in $\mathbf{v}$ (u denotes the vector whose all entries are equal to one). In the following we will consider without loss of generality the slightly different problem where we are looking for extremal rays $\mathbf{e}_{i}$ such that $\mathbf{u}^{T} \mathbf{e}_{i}=a$. Geometrically speaking, we cut the cone with a plane passing through $\mathbf{v}$ such that the intersection is a bounded polytope whose vertices correspond to extremal rays of the initial cone $S$. We are thus given a (bounded) polytope, and a vector $\mathbf{v}$ in this polytope and we want to express this vector $\mathbf{v}$ as a convex combination of vertices of the polytope.

The algorithm essentially relies on two observations: first, we do not need to know all the extremal rays, what we only need is a (small) subset, to express $\mathbf{v}$ as a convex combination of them. Second, all the constraints defining the different cones are linear, and so we can make use of Linear Programming (e.g. [2]). More precisely, the problem of finding a vertex of the polytope defined by the equations

$$
\mathbf{M x}=\mathbf{0}, \quad \mathbf{u}^{T} \mathbf{x}=a, \quad \mathbf{x} \geqslant \mathbf{0}
$$

can be done in time polynomial in the number of constraints and the dimension. Indeed, consider the following linear program :

$$
\begin{align*}
& \min \mathbf{d}^{T} \mathbf{x} \\
& \text { s.t. } \\
& \mathbf{M x}=\mathbf{0}  \tag{11}\\
& \mathbf{x} \geqslant \mathbf{0} \\
& \mathbf{u}^{T} \mathbf{x}=a .
\end{align*}
$$

If $\mathbf{d}$ is not parallel to a constraint of the program (11), then, the solution is a vertex of the corresponding polytope (see for instance [2]). So in practice, if $\mathbf{d}$ is a random direction, an extremal ray is found with probability one.
Let us now present our algorithm which proceeds iteratively by projecting $\mathbf{v}$ on faces $\mathscr{P}_{i}$ of the polytope $\mathscr{P}$ described by the constraints of the program (11). Since the dimension of the faces $\mathscr{P}_{i}$ strictly decreases at each step, the algorithm takes at most $k-1$ steps, where $k$ is the dimension of the cone $S$.

Take any extremal ray $\mathbf{e}_{1}$ of the cone $S$ (for instance by solving the linear program (11)); then the vector $\mathbf{v}$ can be written as the convex combination of $\mathbf{e}_{1}$ and of a vector $\mathbf{v}_{1}$, which belongs to a face $\mathscr{P}_{1}$ of $S: \mathbf{v}=\gamma_{1} \mathbf{e}_{1}+\left(1-\gamma_{1}\right) \mathbf{v}_{1}$. These quantities $\mathbf{v}_{i}, \gamma_{i}$ are easy to compute, as $\mathbf{v}_{1}$ is the solution $\mathbf{x}^{*}$ of the Linear Program

$$
\begin{align*}
& \max \mu \\
& \text { s.t. } \\
& \mathbf{M x}=\mathbf{0}  \tag{12}\\
& \mathbf{x} \geqslant \mathbf{0} \\
& \mathbf{u}^{T} \mathbf{x}=a \\
& \mathbf{v}+\mu\left(\mathbf{v}-\mathbf{e}_{1}\right)=\mathbf{x}
\end{align*}
$$

The geometric meaning of this linear program is as follows: starting fom the vector $\mathbf{v}$ one tries to find a point $\mathbf{x}$ which is diametrically opposite to $\mathbf{e}_{1}$ and as far as possible from $\mathbf{v}$. Clearly this point will be on a face of the polytope (because if it is not, it is possible to go further). Here $\mu$ represents the distance from $\mathbf{v}$ to $\mathbf{x}$.

Now $\mathscr{P}_{i}$ is a new polyhedron, and we still can express $\mathbf{v}_{i}$ as a convex combination of a vertex of $\mathscr{P}_{i}$ (which is also a vertex of $S$ ) and a point $\mathbf{v}_{i+1}$ that belongs to a face $\mathscr{P}_{i+1}$ of $\mathscr{P}_{i}$ (which is also a face of $S$, but of dimension
strictly smaller than $\operatorname{dim} \mathscr{P}_{i}$ ). Thus, after $k^{\prime} \leq k-1$ steps, the dimension of $\mathscr{P}_{k^{\prime}}$ is equal to 0 , which means that $\mathbf{v}_{k^{\prime}}$ is actually a vertex of $\mathscr{P}$ which we denote $\mathbf{e}_{k^{\prime}+1}$. Thus, $\mathbf{v}_{k^{\prime}-1}=\gamma_{k^{\prime}} \mathbf{e}_{k^{\prime}}+\left(1-\gamma_{k^{\prime}}\right) \mathbf{e}_{k^{\prime}+1}$. Finally we can write:

$$
\begin{aligned}
\mathbf{v} & =\mathbf{v}_{0} \\
& =\gamma_{1} \mathbf{e}_{1}+\left(1-\gamma_{1}\right)\left(\gamma_{2} \mathbf{e}_{2}+\left(1-\gamma_{2}\right)\left(\ldots\left(\gamma_{k^{\prime}} \mathbf{e}_{k^{\prime}}+\left(1-\gamma_{k^{\prime}}\right) \mathbf{e}_{k^{\prime}+1}\right)\right)\right) \\
& =\sum_{1}^{k^{\prime}+1} w_{i} \mathbf{e}_{i},
\end{aligned}
$$

with $\sum w_{i}=1$. Finally, as the dimension of the cone $S$ is equal to $k=m-n$, we obtain at most $m-n$ extremal vectors $\mathbf{e}_{i}$. We have thus found the decomposition in polynomial time, which is a dramatic improvement compared to the naive brute force approach that requires the enumeration of all vectors $\mathbf{e}_{i}$.

We now would like to express a vector $\mathbf{v}$ in $\mathscr{F}$ (that is a vector compatible with the measurements in $\mathbf{v}_{m}$ ) as a linear combination of extremal rays of $S$. Moreover we would like to minimize the number of extremal rays in this expression. Equation (9) and the remark below ensure us that there is such a vector $\mathbf{v}$ that can be expressed as a combination of only $p$ extremal rays $\mathbf{e}_{i}$ of $S$. To see this, consider the expression (8) of the polytope $\mathscr{H}$, which describes the set of admissible values of $\mathbf{w}$. It can be defined by only $p$ equalities, so that $\operatorname{dim}(\mathbf{w})-p$ inequality constraints can be activated to define an extremal ray $\mathbf{h}_{i}$ of $\mathscr{H}$. In conclusion, there are admissible vectors $\mathbf{w}$ (the extremal rays of $\mathscr{H}$ ), that only contain at most $p$ nonzero values. However, if one does not want to compute the matrix $\mathbf{E}$ of extremal rays of $S$, this is not an easy task a priori to find such a minimal representation. Indeed, the dimension of $\mathbf{w}$ is exponential in the size of the problem.
In order to compute such a "good" vector $\mathbf{v}$ and its corresponding decomposition, we introduce yet another cone $\mathscr{K} \subset \mathbb{R}^{p}$. This cone is the projection of $S$ by the matrix $\mathbf{P}$ :

$$
\mathscr{K}=\{\mathbf{y}=\mathbf{P v}: \mathbf{v} \geqslant \mathbf{0}, \mathbf{N} \mathbf{v}=\mathbf{0}\} .
$$

The idea of the algorithm is as follows: We know that the vector $\mathbf{v}_{m}$ is in $\mathscr{K}$, and we will express this vector as a convex combination of $p$ vectors, which are the projection of extremal rays $\mathbf{e}_{i}$ under the matrix $\mathbf{P}$. We start from an extremal ray $\mathbf{e}_{1}$ of the cone $\mathscr{F}$ (for instance by applying the Linear Program (11)); then the vector $\mathbf{v}_{m}=\mathbf{y}_{0}$ can be written as the convex combination of $\mathbf{P e}_{1}$ and a vector $\mathbf{y}_{1}$, which belongs to a face $\mathbf{P}_{1}$ of $\mathscr{K}$ : $\mathbf{v}_{m}=\alpha_{1} \mathbf{P e}_{1}+\left(1-\alpha_{1}\right) \mathbf{y}_{1}$. This vector $\mathbf{v}_{1}$ is easy to find with a line search in the cone $\mathscr{K}$ as in Program (12). Now, at each step, find an extremal ray $\mathbf{e}_{i}$ of $\mathscr{K}$ which is mapped to a face $\mathbf{P}_{i-1}$ of $\mathscr{K}$. Then $\mathbf{y}_{i-1}$ can be expressed as a convex combination of $\mathbf{P e}_{i}$ and a vector $\mathbf{y}_{i}$ that belongs to a face $\mathbf{P}_{i}$ of $\mathbf{P}_{i-1}$. Since the dimension of $\mathbf{P}_{i}$ strictly decreases at each step, after $t \leq p$ steps the point $\mathbf{y}_{t}$ is actually an extremal ray of $\mathscr{K}$, and is thus the projection of an extremal ray $\mathbf{e}_{(t+1)}$ of $S$. Finally we have the relations:

$$
\begin{equation*}
\mathbf{v}_{m}=\sum_{1}^{t} \lambda_{i} \mathbf{P} \mathbf{e}_{i}=\mathbf{P}\left(\sum_{1}^{t} \lambda_{i} \mathbf{e}_{i}\right) \tag{13}
\end{equation*}
$$

and thus the vector

$$
\mathbf{v}=\sum_{1}^{t} \lambda_{i} \mathbf{e}_{i}
$$

is a convex combination of at most $p$ extremal vectors of $S$ that satisfies (5).

## 5 Case study

As a matter of illustration and motivation to the methodology presented above, we consider the example of chinese hamster ovary (CHO) cells cultivated in batch mode in stirred flasks in a serum-free medium ([1]). During the growth phase, we assume that the cell metabolism is described by the metabolic network presented in Appendix A. The network involves the Glycolysis pathway, the Pentose-Phosphate pathway, the Krebs cycle, the amino-acid metabolism, the urea cycle as well as the nucleotide, protein and lipid synthesis (see [13] for further motivation and details).
For this network we have $m=82$ fluxes and $n=53$ internal metabolites, and there are 65329 elementary flux vectors $\mathbf{e}_{i}$ (i.e the polyhedral cone $S$ has 65329 edges).

Moreover, there are $p=22$ extra-cellular species whose degradation or accumulation rates in the culture medium are measured and collected in the vector $\mathbf{v}_{m}$ given in Table 1.
The algorithm of Section 4 is then implemented with these data. We present a trial where the resulting admissible flux vector $\mathbf{v}$ is given in Table 2. It can be checked to satisfy (5) and to be is fully consistent with the experimental

| Glucose | $-0,187130$ |  |  |
| :--- | ---: | :--- | ---: |
| Threonine | $-0,001184$ |  |  |
| Valine | $-0,001956$ |  |  |
| Leucine | $-0,002601$ | Glutamine | $-0,050246$ |
| Methionine | $-0,000724$ | Isoleucine | $-0,002125$ |
| Arginine | $-0,002142$ | $-0,001528$ |  |
| Phenylalanine | $-0,000998$ |  |  |
| Asparagine | $-0,001278$ |  |  |
| Aspartate | $-0,003298$ |  | Proline |
| Glyrosine | $-0,002142$ |  |  |
| Glycine | $-0,000318$ |  | $-0,007610$ |
| Glutamate | 0,00230 | Cysteine | $-0,000923$ |
| Lactate | 0,344510 | Serine | $-0,000923$ |
|  | Ammonia | 0,045712 |  |

Table 1: Vector of measurements $\mathbf{v}_{m}\left(\mathrm{mM} /\left(\mathrm{h} \times 10^{9}\right.\right.$ cells $)$ ), with a " - " sign for degradation and a " + " sign for accumulation.
data of Table 1. Furthermore, the algorithm provides the minimal decomposition of $\mathbf{v}$ as a non-negative linear combination of the 22 elementary flux vectors $\mathbf{e}_{i}$ given in Tables 3 and 4 .

Let us insist that the obtained vector $\mathbf{v}$ is obviously just one possible solution among many others with a minimal decomposition. If the algorithm is re-run with the same initial data, it will find other solutions with a minimal decomposition because it makes use of random searching directions. Complementary results on the metabolic flux analysis of CHO cells can be found in the companion paper [13].

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## Appendix A. Metabolic network.

Glycolisis
v1: Glu + ATP $\rightarrow$ G6P + ADP
v2: G6P + ATP $\rightarrow$ DHAP + G3P + ADP
v3: DHAP $\rightarrow$ G3P
v4: G3P $+\mathrm{OxP}+\mathrm{P}_{i}+\mathrm{ADP} \rightarrow(3) \mathrm{PG}+\mathrm{RdP}+\mathrm{ATP}$
v5: (3)PG + ADP $\rightarrow \mathrm{Pyr}+$ ATP
Krebs Cycle
$\mathrm{v} 6: \mathrm{Pyr}+\mathrm{OxP} \rightarrow \mathrm{AcCoA}+\mathrm{CO}_{2}+\mathrm{RdP}$
v7: AcCoA + Oxal $\rightarrow$ Cit
v8: $\mathrm{Cit}+\mathrm{OxP} \rightarrow \alpha \mathrm{KG}+\mathrm{CO}_{2}+\mathrm{RdP}$
$\mathrm{v} 9: \alpha \mathrm{KG}+\mathrm{OxP} \rightarrow \mathrm{SucCoA}+\mathrm{CO}_{2}+\mathrm{RdP}$
v10:SucCoA + ADP $+\mathrm{P}_{i} \rightarrow$ Succ + ATP
v11:Succ $\rightarrow$ Fum
v12:Fum $\rightarrow$ Mal
v13:Mal + OxP $\rightarrow$ Oxal + RdP
Pyruvate Fates
v14:Pyr + RdP $\rightarrow$ Lact + OxP
$\mathrm{v} 15: \mathrm{Pyr}+\mathrm{Glu} \rightarrow \mathrm{Ala}+\alpha \mathrm{KG}$
Pentose Phosphate Pathway
v16: G6P +2 OxP $\rightarrow \mathrm{R} 5 \mathrm{P}+2 \mathrm{RdP}+\mathrm{CO}_{2}$
v17: $3 \mathrm{R} 5 \mathrm{P} \rightarrow 2.5 \mathrm{G} 6 \mathrm{P}+0.5 \mathrm{P}_{i}$
Anaplerotic Reaction
v18: $\mathrm{Mal}+\mathrm{OxP} \rightarrow \mathrm{Pyr}+\mathrm{CO}_{2}+\mathrm{RdP}$
Amino Acid Metabolism
v19:Glu $+\mathrm{OxP} \rightarrow \alpha \mathrm{KG}+\mathrm{NH}_{4}^{+}+\mathrm{RdP}$
$\mathrm{v} 20: \mathrm{Oxal}+\mathrm{Glu} \rightarrow \mathrm{Asp}+\alpha \mathrm{KG}$
v21: $\mathrm{Gln} \rightarrow \mathrm{Glu}+\mathrm{NH}_{4}^{+}$
v22: Thr $+\mathrm{OxP} \rightarrow \mathrm{Gly}+\mathrm{AcCoA}+\mathrm{RdP}$
v23: $\mathrm{Gly}+\mathrm{OxP} \rightarrow \mathrm{CO}_{2}+\mathrm{NH}_{4}^{+}+\mathrm{RdP}$
v24: (3) $\mathrm{PG}+\mathrm{OxP}+\mathrm{Glu} \rightarrow \mathrm{Ser}+\alpha \mathrm{KG}+\mathrm{RdP}+\mathrm{P}_{i}$
v25: Ser $\rightarrow$ Gly
v26: $\mathrm{Ser} \rightarrow \mathrm{Pyr}+\mathrm{NH}_{4}^{+}$
v27: $\mathrm{Thr} \rightarrow \alpha \mathrm{Kb}+\mathrm{NH}_{4}^{+}$
v28: $\alpha \mathrm{Kb}+\mathrm{OxP} \rightarrow \mathrm{PropCoA}+\mathrm{RdP}+\mathrm{CO}_{2}$
v29: PropCoA $+\mathrm{CO}_{2}+$ ATP $\rightarrow$ SucCoA + ADP $+\mathrm{P}_{i}$
v30: $\mathrm{Lys}+2 \alpha \mathrm{KG}+\mathrm{OxP} \rightarrow \alpha \mathrm{Ka}+2 \mathrm{Glu}+\mathrm{RdP}$ v31: $\alpha \mathrm{Ka}+2 \mathrm{OxP} \rightarrow$ AcetoAcCoA $+2 \mathrm{RdP}+2 \mathrm{CO}_{2}$
v32: AcetoAcCoA $\rightarrow 2$ AcCoA
v33: Val $+\alpha \mathrm{KG} \rightarrow \alpha \mathrm{Kv}+\mathrm{Glu}$
v34: $\alpha \mathrm{Kv}+3 \mathrm{OxP} \rightarrow$ PropCoA $+2 \mathrm{CO}_{2}+3 \mathrm{RdP}$
v35: Ile $+\alpha \mathrm{KG} \rightarrow$ (3)Methyl(2)oxovalerate+Glu
v36: (3)Methyl(2)oxovalerate $+2 \mathrm{OxP} \rightarrow \mathrm{AcCoA}+\mathrm{PropCoA}+\mathrm{CO}_{2}+2 \mathrm{RdP}$
v37: $\mathrm{Leu}+\alpha \mathrm{KG} \rightarrow \alpha \mathrm{Ki}+\mathrm{Glu}$
v38: $\alpha \mathrm{Ki}+\mathrm{OxP}+\mathrm{ATP} \rightarrow \mathrm{AcCoA}+\mathrm{AcetoAc}+\mathrm{RdP}+\mathrm{ADP}+\mathrm{P}_{i}$
v39: AcetoAc + SucCoA $\rightarrow$ AcetoAcCoA + Succ
v40: Phe $+\mathrm{RdP} \rightarrow \mathrm{Tyr}+\mathrm{OxP}$
$\mathrm{v} 41: \mathrm{Tyr}+\alpha \mathrm{KG} \rightarrow \mathrm{Fum}+\mathrm{Glu}+\mathrm{AcetoAc}+\mathrm{CO}_{2}$
v42: Met + ATP $\rightarrow$ HomoCys + AMP $+\mathrm{P}_{i}$
v43: $\mathrm{HomoCys}+\mathrm{Ser} \rightarrow \alpha \mathrm{Kb}+\mathrm{Cys}+\mathrm{NH}_{4}^{+}$
v44: $\mathrm{Cys} \rightarrow \mathrm{Pyr}+\mathrm{NH}_{4}^{+}$
v45: Asn $\rightarrow$ Asp $+\mathrm{NH}_{4}^{+}$
v46: Arg $\rightarrow$ Ornitine + Urea
v47: Ornitine $+\alpha$ KG $\rightarrow$ Glu $\gamma$ SA + Glu
v48: Pro $\rightarrow$ Glu $\gamma$ SA
v49: Glu $\gamma \mathrm{SA}+\mathrm{OxP} \rightarrow \mathrm{Glu}+\mathrm{RdP}$
v50: $\mathrm{His} \rightarrow \mathrm{Glu}+\mathrm{NH}_{4}^{+}$
v51: Asp $_{\text {ext }} \rightarrow$ Asp
v52: Cys $_{\text {ext }} \rightarrow$ Cys

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v53: Gly }->\mp@subsup{\mathrm{ Gly ext }}{\mathrm{ ex}}{
v54: Ser ext }->\mathrm{ Ser
v55: Glu ext }->\mathrm{ Glu
v56: Tyr ext }->\mathrm{ Tyr
v57: Ala }->\mp@subsup{\mathrm{ Ala}}{\mathrm{ ext }}{
```

Protein Synthesis
v58:0.023 His $+0.053 \mathrm{Ile}+0.091 \mathrm{Leu}+0.059 \mathrm{Lys}+0.023 \mathrm{Met}+0.039 \mathrm{Phe}+0.059 \mathrm{Thr}+0.014 \mathrm{Tr} p$
$+0.066 \mathrm{Val}+0.051 \mathrm{Arg}+0.019 \mathrm{Cys}+0.042 \mathrm{Gln}+0.072 \mathrm{Gly}+0.052 \mathrm{Pro}+0.032 \mathrm{Tyr}+0.78 \mathrm{Ala}$
$+0.043 \mathrm{Asn}+0.053 \mathrm{Asp}+0.063 \mathrm{Glu}+0.068 \mathrm{Ser}+3 \mathrm{ATP} \rightarrow$ Protein $+\mathrm{AMP}+\mathrm{Pp}_{i}+2 \mathrm{ADP}+2 \mathrm{P}_{i}$
Nucleotide Synthesis
v59: R5P + ATP $\rightarrow$ PRPP + AMP
v60: PRPP $+2 \mathrm{Gln}+$ Asp + Gly +4 ATP $+\mathrm{CO}_{2} \rightarrow \mathrm{IMP}+2 \mathrm{Glu}+\mathrm{Fum}+4 \mathrm{ADP}+4 \mathrm{P}_{i}+\mathrm{Pp}_{i}$
v61: IMP + Asp +3 ATP $\rightarrow$ ATP $_{R N}+$ Fum +3 ADP $+\mathrm{P}_{i}$
v62: IMP $+\mathrm{Gln}+3 \mathrm{ATP}+\mathrm{OxP} \rightarrow \mathrm{GTP}_{R N}+\mathrm{Glu}+2 \mathrm{ADP}+\mathrm{AMP}+\mathrm{Pp}_{i}+\mathrm{RdP}$
v63: $\mathrm{CO}_{2}+\mathrm{NH}_{4}^{+}+\mathrm{Asp}+2$ ATP $+\mathrm{OxP} \rightarrow$ Orotate $+\mathrm{RdP}+2 \mathrm{ADP}+2 \mathrm{P}_{i}$
v64: Orotate $+\mathrm{PRPP}+\mathrm{ATP} \rightarrow \mathrm{UTP}_{R N}+\mathrm{CO}_{2}+2 \mathrm{ADP}+\mathrm{Ppi}$
v65: $\mathrm{UTP}_{R N}+\mathrm{Gln}+\mathrm{ATP} \rightarrow \mathrm{CTP}_{R N}+\mathrm{Glu}+\mathrm{ADP}+\mathrm{P}_{i}$
v66: $0.285 \mathrm{ATP}_{R N}+0.285 \mathrm{UTP}_{R N}+0.215 \mathrm{GTP}_{R N}+0.215 \mathrm{CTP}_{R N} \rightarrow$ RNA
v67: $\mathrm{ATP}_{R N} \rightarrow$ dATP
v68: $\mathrm{GTP}_{R N} \rightarrow \mathrm{dGTP}$
v69: $\mathrm{UTP}_{R N} \rightarrow \mathrm{dTTP}$
v70: $\mathrm{CTP}_{R N} \rightarrow \mathrm{dCTP}$
v71: 0.285 dATP +0.285 dTTP $+0.215 \mathrm{dGTP}+0.215 \mathrm{dCTP} \rightarrow$ DNA
Lipid Synthesis
v72: $\mathrm{DHAP}+\mathrm{RdP} \rightarrow$ Glyc3P + OxP
v73: Glyc3P + $18 \mathrm{AcCoA}+21 \mathrm{ATP}+33 \mathrm{RdP} \rightarrow \mathrm{PA}+16\left(\mathrm{ADP}+\mathrm{P}_{i}\right)+33 \mathrm{OxP}+5\left(\mathrm{AMP}+\mathrm{Pp}_{i}\right)$
v74: $\mathrm{PA} \rightarrow(1,2) \mathrm{DG}+\mathrm{P}_{i}$
v75: Eth $+(1,2) \mathrm{DG}+2$ ATP $\rightarrow \mathrm{PE}+\mathrm{ADP}+\mathrm{P}_{i}+\mathrm{AMP}+\mathrm{Pp}_{i}$
v76: $\mathrm{Chol}+1,2) \mathrm{DG}+2$ ATP $\rightarrow \mathrm{PC}+\mathrm{ADP}+\mathrm{P}_{i}+\mathrm{AMP}+\mathrm{Pp}_{i}$
v77: PE + Ser $\rightarrow$ PS + Eth
v78: $8 \mathrm{AcCoA}+8$ ATP $+15 \mathrm{RdP}+\mathrm{Ser} \rightarrow$ Sphg $+7\left(\mathrm{ADP}+\mathrm{P}_{i}\right)+15 \mathrm{OxP}+\mathrm{CO}_{2}+\mathrm{AMP}+\mathrm{Pp}_{i}$
v79: $\mathrm{Sphg}+8 \mathrm{AcCoA}+8 \mathrm{ATP}+14 \mathrm{RdP} \rightarrow \mathrm{Cer}+7\left(\mathrm{ADP}+\mathrm{P}_{i}\right)+14 \mathrm{OxP}+\mathrm{AMP}+\mathrm{Pp}_{i}$
v80: $\mathrm{Cer}+\mathrm{PC} \rightarrow \mathrm{SM}+(1,2) \mathrm{DG}$
v81: 6 AcetoAcCoA +6 AcCoA +18 ATP $+14 \mathrm{RdP} \rightarrow$ Cholesterol +14 OxP+ 18 ADP +4 Pp $i$
$+6 \mathrm{P}_{i}+6 \mathrm{CO}_{2}$
v82: $0.5 \mathrm{PC}+0.2 \mathrm{PE}+0.075 \mathrm{PS}+0.075 \mathrm{SM}+0.15$ Cholesterol $\rightarrow$ Membrane Lipid

| v1 | 0.18713 | v21 | 0.01570 | v41 | 0.00849 | v61 | 0.00687 | v81 | 0.00025 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| v2 | 0.14891 | v22 | 0.00000 | v42 | 0.00068 | v62 | 0.00518 | v82 | 0.00167 |
| v3 | 0.14762 | v23 | 0.00000 | v43 | 0.00068 | v63 | 0.01205 |  |  |
| v4 | 0.29653 | v24 | 0.04879 | v44 | 0.00157 | v64 | 0.01205 |  |  |
| v5 | 0.24774 | v25 | 0.01440 | v45 | 0.00120 | v65 | 0.00518 |  |  |
| v6 | 0.00000 | v26 | 0.03426 | v46 | 0.00205 | v66 | 0.00000 |  |  |
| v7 | 0.00000 | v27 | 0.00108 | v47 | 0.00205 | v67 | 0.00687 |  |  |
| v8 | 0.00000 | v28 | 0.00176 | v48 | 0.00205 | v68 | 0.00518 |  |  |
| v9 | 0.06698 | v29 | 0.00504 | v49 | 0.00410 | v69 | 0.00687 |  |  |
| v10 | 0.06109 | v30 | 0.00202 | v50 | 0.00326 | v70 | 0.00518 |  |  |
| v11 | 0.07202 | v31 | 0.00202 | v51 | 0.00023 | v71 | 0.02411 |  |  |
| v12 | 0.09943 | v32 | 0.01145 | v52 | 0.00089 | v72 | 0.00129 |  |  |
| v13 | 0.02953 | v33 | 0.00184 | v53 | 0.00235 | v73 | 0.00129 |  |  |
| v14 | 0.34451 | v34 | 0.00184 | v54 | 0.00013 | v74 | 0.00129 |  |  |
| v15 | 0.00894 | v35 | 0.00144 | v55 | 0.00944 | v75 | 0.00046 |  |  |
| v16 | 0.10879 | v36 | 0.00144 | v56 | 0.00755 | v76 | 0.00096 |  |  |
| v17 | 0.02823 | v37 | 0.00244 | v57 | 0.00881 | v77 | 0.00013 |  |  |
| v18 | 0.06988 | v38 | 0.00244 | v58 | 0.00173 | v78 | 0.00013 |  |  |
| v19 | 0.00000 | v39 | 0.01093 | v59 | 0.02411 | v79 | 0.00013 |  |  |
| v20 | 0.02955 | v40 | 0.00093 | v60 | 0.01205 | v80 | 0.00013 |  |  |

Table 2: A vector $\mathbf{v}$ of admissible metabolic flux rates $\left(\mathrm{mM} /\left(\mathrm{h} \times 10^{9}\right.\right.$ cells $)$ ) consistent with the metabolic network and the experimental data of Table 1.


Table 3: Elementary vectors $\mathbf{e}_{i}$ (first 41 entries) of the minimal decomposition of the flux vector $\mathbf{v}$ of Table 2. The integer entries are exact stoichiometric coefficients. The other entries are truncated to the 2 nd decimal.

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Table 4: Elementary vectors $\mathbf{e}_{i}$ (last 41 entries) of the minimal decomposition of the flux vector $\mathbf{v}$ of Table 2. The integer entries are exact stoichiometric coefficients. The other entries are truncated to the 2nd decimal.

